

# Binary Search Trees: Split and Merge

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**Data Structures Fundamentals**  
**Algorithms and Data Structures**

# Learning Objectives

- Implement merging and splitting of AVL trees.
- Analyze the runtime of these operations.

# New Operations

Another useful feature of binary search trees is the ability to recombine them in interesting ways.

# New Operations

Another useful feature of binary search trees is the ability to recombine them in interesting ways. We discuss two new operations:

- **Merge** Combines two binary search trees into a single one.
- **Split** Breaks one binary search tree into two.

# Outline

1 Merge

2 Split

# Merge

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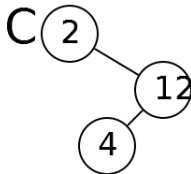
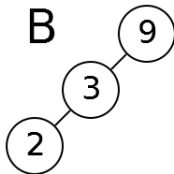
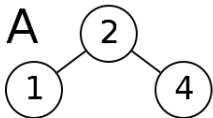
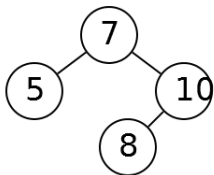
## Merge

**Input:** Roots  $R_1$  and  $R_2$  of trees with all keys in  $R_1$ 's tree smaller than those in  $R_2$ 's

**Output:** The root of a new tree with all the elements of both trees

# Problem

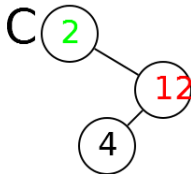
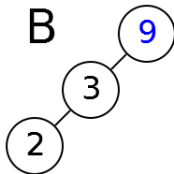
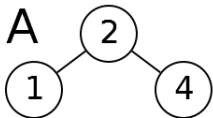
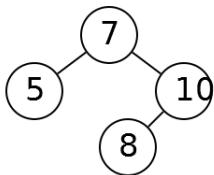
Which tree can be merged with the given one?





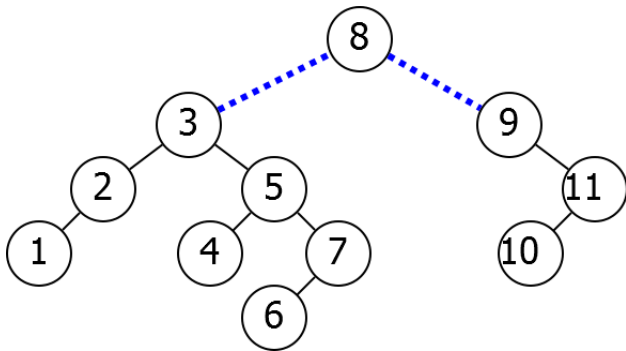
# Problem

Which tree can be merged with the given one?



# Extra Root

Easy if you have an extra node to add as root.



# Implementation

MergeWithRoot( $R_1, R_2, T$ )

$T.\text{Left} \leftarrow R_1$

$T.\text{Right} \leftarrow R_2$

$R_1.\text{Parent} \leftarrow T$

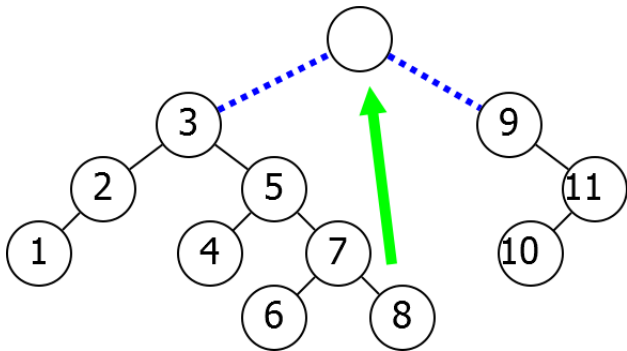
$R_2.\text{Parent} \leftarrow T$

return  $T$

Time  $O(1)$ .

# Get Root

Get new root by removing largest element of left subtree.



# Merge

Merge( $R_1, R_2$ )

$T \leftarrow \text{Find}(\infty, R_1)$

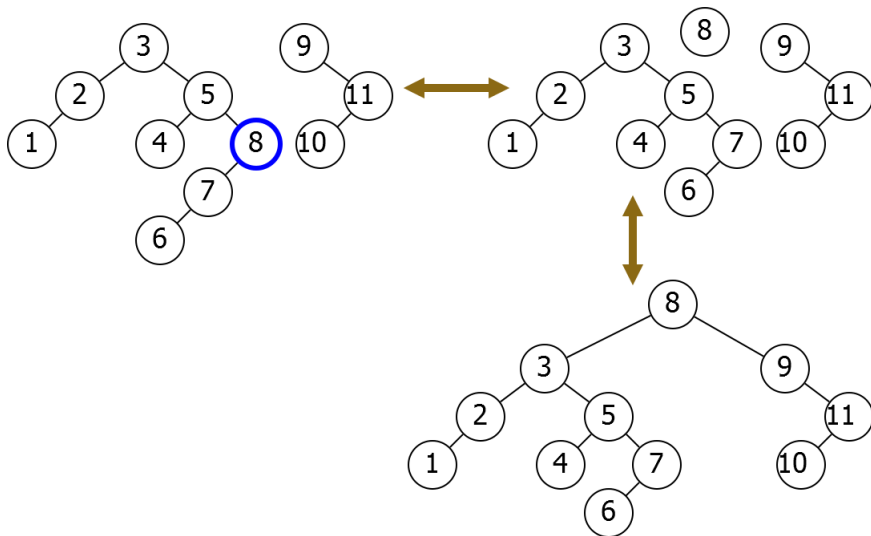
Delete( $T$ )

MergeWithRoot( $R_1, R_2, T$ )

return  $T$

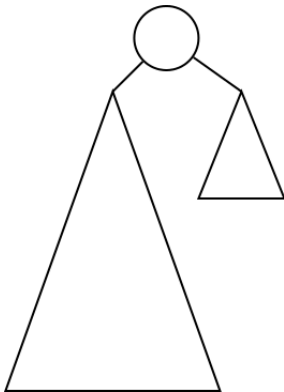
Time  $O(h)$ .

# Merge



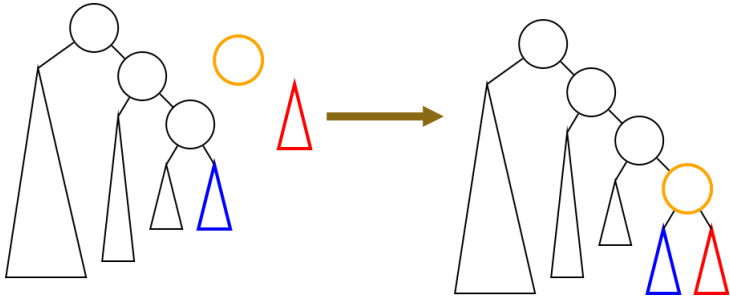
# Balance

Unfortunately, this merge does not preserve balance properties.



# Idea

Go down side of tree until merge with subtree of same height.





# Implementation

**AVLTreeMergeWithRoot( $R_1, R_2, T$ )**

```
if  $|R_1.\text{Height} - R_2.\text{Height}| \leq 1$ :  
    MergeWithRoot( $R_1, R_2, T$ )  
     $T.\text{Ht} \leftarrow \max(R_1.\text{Height}, R_2.\text{Height}) + 1$   
return  $T$ 
```

# Implementation (continued)

**AVLTreeMergeWithRoot( $R_1, R_2, T$ )**

```
else if  $R_1.$ Height  $> R_2.$ Height:  
     $R' \leftarrow \text{AVLTreeMWR}(R_1.\text{Right}, R_2, T)$   
     $R_1.\text{Right} \leftarrow R'$   
     $R'.\text{Parent} \leftarrow R_1$   
    Rebalance( $R_1$ )  
    return root  
else if  $R_1.$ Height  $< R_2.$ Height:  
    ...
```

# Analysis

- Each step changes height difference by 1 or 2.
- Eventually within 1.
- Time  $O(|R_1.\text{Height} - R_2.\text{Height}| + 1)$ .

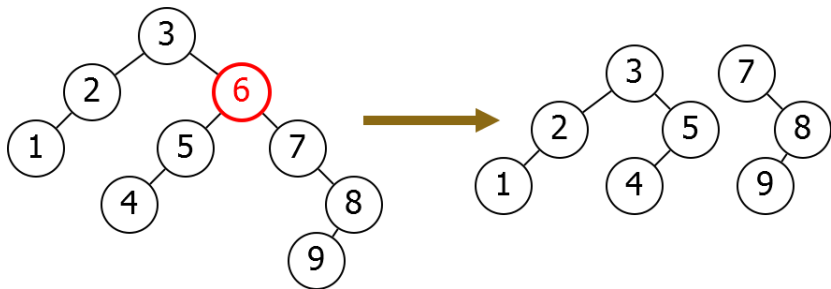
# Outline

1 Merge

2 Split

# Split

Break tree into two trees:



# Formal Definition

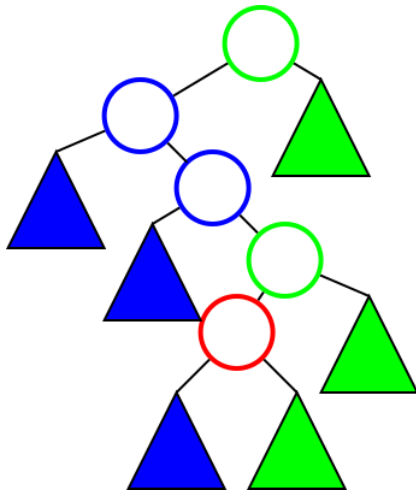
## Split

**Input:** Root  $R$  of a tree, key  $x$

**Output:** Two trees, one with elements  $\leq x$ ,  
one with elements  $> x$ .

# Idea

Search for  $x$ , merge subtrees.



# Implementation

**Split( $R, x$ )**

```
if  $R = \text{null}$ :  
    return ( $\text{null}, \text{null}$ )  
if  $x \leq R.\text{Key}$ :  
    ( $R_1, R_2$ )  $\leftarrow$  Split( $R.\text{Left}, x$ )  
     $R_3 \leftarrow$  MergeWithRoot( $R_2, R.\text{Right}, R$ )  
    return ( $R_1, R_3$ )  
if  $x > R.\text{Key}$ :  
    ...
```



# AVL Trees

- Using `AVLMergeWithRoot` maintains balance.
- $\text{Time} = \sum O(|h_i - h_{i+1}| + 1) = O(h_{\max}) = O(\log(n)).$

# Conclusion

## Summary

- Merge combines trees.
- Split turns one tree into two.
- Both can be implemented in  $O(\log(n))$  time for AVL trees.